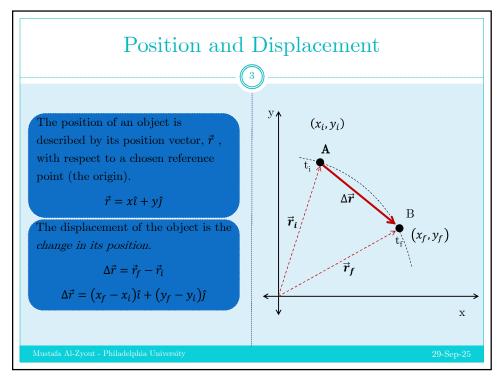


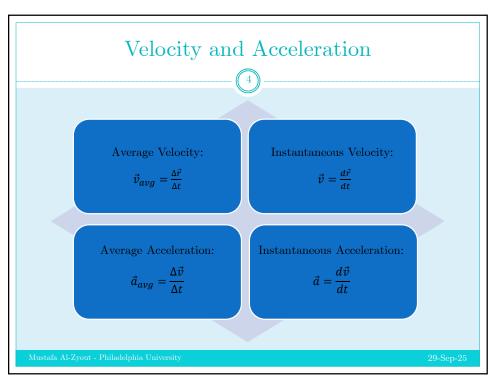
Lecture 01

- Position, Velocity and Acceleration
- Kinematic Equations

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29-Sep-25





Kinematic Equations for 2-D Motion



- These equations will be similar to those of one-dimensional kinematics.
- •Motion in two dimensions can be modeled as two independent motions in each of the two perpendicular directions associated with the x and y axes.
 - Any influence in the y direction does not affect the motion in the x direction.

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Kinematic Equations



Since acceleration is constant, we can also find an expression for the velocity as a function of time:

$$\vec{v}_f = \vec{v}_i + \vec{a}t$$

The position vector can also be expressed as a function of time:

$$\vec{r}_f = \vec{r}_i + \vec{v}_i t + \frac{1}{2} \vec{a} t^2$$

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Kinematic Equations: 2-D 7				
	Equations	Missing		
	$\vec{v}_f = \vec{v}_i + \vec{a}t$	$\Delta \vec{r}$: displacement (m)		
	$\Delta \vec{r} = \vec{v}_i t + \frac{1}{2} \vec{a} t^2$	$ec{v}_{\mathrm{f}}:$ final velocity (m/s)		
	$\Delta \vec{r} = \vec{v}_f t - \frac{1}{2} \vec{a} t^2$	$ec{v}_i$: initial velocity (m/s)		
	$\Delta \vec{r} = \frac{1}{2} (\vec{v}_i + \vec{v}_f) t$	\vec{a} : acceleration (m/s ²)		

Kinematic Equations: Horizontal components				
Equations	Missing			
$v_{fx} = v_{ix} + a_x t$	Δx : displacement (m)			
$v_{fx}^2 = v_{ix}^2 + 2a_x \Delta x$	$t: \mathrm{time}\; (\mathrm{s})$			
$\Delta x = v_{ix}t + \frac{1}{2}a_xt^2$	$v_{ m fx}$: final velocity (m/s)			
$\Delta x = v_{fx}t - \frac{1}{2}a_xt^2$	$v_{i\mathbf{x}}$: initial velocity (m/s)			
$\Delta x = \frac{1}{2} (v_{ix} + v_{fx}) t$	a_x : acceleration (m/s ²)			
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Kinematic Equations: Vertical components				
	Equations	Missing		
	$v_{fy} = v_{iy} + a_y t$	Δy : displacement (m)		
	$v_{fy}^2 = v_{iy}^2 + 2a_y \Delta y$	$t: ext{time (s)}$		
	$\Delta y = v_{iy}t + \frac{1}{2}a_yt^2$	v_{fy} : final velocity (m/s)		
	$\Delta y = v_{fy}t - \frac{1}{2}a_yt^2$	v_{iy} : initial velocity (m/s)		
	$\Delta y = \frac{1}{2} (v_{iy} + v_{fy}) t$	a_y : acceleration (m/s ²)		
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Average velocity Friday, 29 January, 2021 21:33	Lecturer: Mustafa Al-Zyout, Philadelphia University, Jordan. R. A. Serway and J. W. Jewett, Jr., Physics for Scientists and Engineers, 9th Ed., CENGAGE Learning, 2014. J. Walker, D. Halliday and R. Resnick, Fundamentals of Physics, 10th ed., WILEY, 2014. H. D. Young and R. A. Freedman, University Physics with Modern Physics, 14th ed., PEARSON, 2016. H. A. Radi and J. O. Rasmussen, Principles of Physics For Scientists and Engineers, 1st ed., SPRINGER, 2013.
A motorist drives south at $20 m/s$ for $3 min.$, then	H. A. Radi and J. O. Rasmussen, <i>Principles of Physics For Scientists and Engineers</i> , 1st ed., SPRINGER, 2013 turns west and travels at 25 m/s for 2min., and finally travels
northwest at $30 m/s$ for $1 min$ For this $6 min$. trip	o, find:
• the total vector displacement,	
• the average speed	
• the average velocity.	

Average acceleration Saturday, 30 January, 2021 12:22		J. Walker, D. Halliday and R. Resnick, $Fundamentals\ of\ Physics,\ 10th\ ed.$, WILEY, 2014.
A car is traveling east at (60 km/h), it rounds a curve	e and	l after (5 s), it is traveling north at the
same speed. Find the average acceleration of the car.		

Position, velocity and acceleration

Saturday, 30 January, 2021 12:23

Lecturer: Mustafa Al-Zyout, Philadelphia University, Jordan.

- [R. A. Serway and J. W. Jewett, Jr., Physics for Scientists and Engineers, 9th Ed., CENGAGE Learning, 2014.
- □ J. Walker, D. Halliday and R. Resnick, Fundamentals of Physics, 10th ed., WILEY,2014.
- H. D. Young and R. A. Freedman, University Physics with Modern Physics, 14th ed., PEARSON, 2016.
- H. A. Radi and J. O. Rasmussen, Principles of Physics For Scientists and Engineers, 1st ed., SPRINGER, 2013.

A rabbit runs across a parking lot on which a set of coordinate axes has, strangely enough, been drawn. The coordinates (meters) of the rabbit's position as functions of time t (seconds) are given by

$$x = -0.31t^2 + 7.2t + 28$$

$$y = 0.22t^2 - 9.1t + 30.$$

- (a) At t = 15s, what is the rabbit's position vector \vec{r} , in unit vector notation and in magnitude-angle notation?
- (b) find the velocity \vec{v} at time t = 15s.
- (c) find the acceleration \vec{a} at time t = 15 s.

SOLUTION

At t = 15 s, the scalar components are

$$x = (-0.31)(15)^2 + (7.2)(15) + 28 = 66m$$

And

$$y = (0.22)(15)^2 - (9.1)(15) + 30 = -57m,$$

So:

$$\vec{r} = (66m)\hat{\imath} - (57m)\hat{\jmath}$$

To get the magnitude and angle of \vec{r} , we use:

$$r = \sqrt{x^2 + y^2} = \sqrt{(66m)^2 + (-57m)^2}$$

$$= 87m$$
,

And

$$\theta = \tan^{-1} \frac{y}{x} = \tan^{-1} \left(\frac{-57m}{66m} \right) = -41^{\circ}.$$

Although $\theta=139^{\circ}$ has the same tangent as -41° , the components of position vector \vec{r} indicate that the desired angle is $139^{\circ} - 180^{\circ} = -41^{\circ}$.

SOLUTION

$$v_x = \frac{dx}{dt} = \frac{d}{dt}(-0.31t^2 + 7.2t + 28)$$

$$= -0.62t + 7.2.$$

At t = 15 s, this give $v_x = -2.1$ m/s.. Similarly, applying the v_y part, we find

$$v_y = \frac{dy}{dt} = \frac{d}{dt}(0.22t^2 - 9.1t + 30)$$
$$= 0.44t - 9.1.$$

At t = 15s, this gives

$$v_y = -2.5m/s$$
.

$$\vec{v} = (-2.1m/s)\hat{i} + (-2.5m/s)\hat{j},$$

To get the magnitude and angle

$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{(-2.1m/s)^2 + (-2.5m/s)^2} = 3.3m/s$$

$$\theta = \tan^{-1} \frac{v_y}{v_x} = \tan^{-1} \left(\frac{-2.5m/s}{-2.1m/s} \right)$$
$$= \tan^{-1} 1.19 = -130^{\circ}.$$

SOLUTION

the x component of \vec{a} to be

$$a_x = \frac{dv_x}{dt} = \frac{d}{dt}(-0.62t + 7.2) = -0.62m/s^2.$$

the y component as

$$a_y = \frac{dv_y}{dt} = \frac{d}{dt}(0.44t - 9.1) = 0.44m/s^2.$$

We see that the acceleration does not vary with time

$$\vec{a} = (-0.62m/s^2)\hat{\imath} + (0.44m/s^2)\hat{\jmath}$$

For the magnitude we have

$$a = \sqrt{a_x^2 + a_y^2} = \sqrt{(-0.62m/s^2)^2 + (0.44m/s^2)^2} = 0.76m/s^2.$$

For the angle we have

$$\theta = tan^{-1} \frac{a_y}{a_x} = tan^{-1} \left(\frac{0.44m/s^2}{-0.62m/s^2} \right) = -35^\circ.$$

However, this angle, which is the one displayed on a calculator, indicates that \vec{a} is directed to the right and downward. Yet, we know from the components that \vec{a} must be directed to the left and upward. To find the other angle that has the same tangent as -35° but is not displayed on a calculator, we add 180°:

$$-35^{\circ} + 180^{\circ} = 145^{\circ}$$
.

Saturday, 30 January, 2021 12:24

Lecturer: Mustafa Al-Zyout, Philadelphia University, Jordan.

- R. A. Serway and J. W. Jewett, Jr., Physics for Scientists and Engineers, 9th Ed., CENGAGE Learning, 2014.
- J. Walker, D. Halliday and R. Resnick, Fundamentals of Physics, 10th ed., WILEY, 2014.
- H. D. Young and R. A. Freedman, University Physics with Modern Physics, 14th ed., PEARSON, 2016.
- H. A. Radi and J. O. Rasmussen, Principles of Physics For Scientists and Engineers, 1st ed., SPRINGER, 2013.

A particle moves in the xy plane, starting from the origin at t = 0 with an initial velocity having an x component of $20 \, m/s$ and a y component of $-15 \, m/s$. The particle experiences an acceleration in the x direction, given by $a_x = 4 \, m/s^2$.

- (A) Determine the total velocity vector at any time.
- (B) Calculate the velocity and speed of the particle at t = 5 s and the angle the velocity vector makes with the x axis.
- (C) Determine the x and y coordinates of the particle at any time (t) and its position vector at this time.

SOLUTION

We set $v_{xi} = 20m/s$, $v_{yi} = -15m/s$, $a_x = 4.0m/s^2$, and $a_y = 0$.

the velocity vector:

$$\vec{v}_f = \vec{v}_i + \vec{a}_t = (v_{xi} + a_x t)\hat{i} + (v_{yi} + a_y t)\hat{j}$$

Substitute numerical values with the velocity in (m/s) and the time in seconds:

$$\vec{v}_f = [20 + (4.0)t]\hat{i} + [-15 + (0)t]\hat{j} = [(20 + 4.0t)\hat{i} - 15\hat{j}]$$

Notice that the x component of velocity increases in time while the y component remains constant;

SOLUTION

At t = 5.0s:

$$\vec{v}_f = [(20 + 4.0(5.0))\hat{i} - 15\hat{j}] = (40\hat{i} - 15\hat{j})m/s$$

Determine the angle θ that \vec{v}_f makes with the x axis at t = 5.0s:

$$\theta = tan^{-1} \left(\frac{v_{yf}}{v_{xf}} \right) = tan^{-1} \left(\frac{-15m/s}{40m/s} \right) = -21^{\circ}$$

Evaluate the speed of the particle as the magnitude of \vec{v}_f :

$$v_f = |\vec{v}_f| = \sqrt{v_{xf}^2 + v_{yf}^2} = \sqrt{(40)^2 + (-15)^2 m/s} = 43m/s$$

The negative sign for the angle θ indicates that the velocity vector is directed at an angle of 21° below the positive x axis.

